Amendments to the Claims:

This listing of all pending claims (including withdrawn claims) will replace all prior versions, and listings, of claims in the application. Cancelled and not entered claims are indicated with claim number and status only. The claims show added text with underlining and deleted text with strikethrough. The status of each claim is indicated with one of (original), (currently amended), (cancelled), (withdrawn), (new), (previously presented), or (not entered).

Listing of Claims:

- 1. (Currently Amended) A robot toy, comprising:
- a control unit formed by a movable leg of the robot toy,
- a clutch to transmit motor power;
- a switch:
- a four section link including a link, a frame that faces the link, and two swinging links that face each other;
 - a first toy component arranged ondirectly connected to the link; and
- a second toy component arranged on one of the two swinging links that face each other; wherein

the clutch is engaged by moving the control unit to change the form of the toy robot, and the motor power is transmitted so that a part of the robot toy conducts at least one among up and down movement, rotating movement, or opening and closing movement,

the switch is switched by moving the control unit, and at least one among number of revolutions of the motor, luminescent color in the robot toy, or sound production, is changed before and after the form change,

the one of the two swinging links extends to an opposite side with respect to the frame and a tip thereof rotatably and swingably <u>directly</u> engages with a rotation disk at an eccentric position, and

the first and second toy components are rotated and perform opening and closing movements relative to each other by rotating the rotating disk, before or after the form change.

- 2. (Previously Presented) The robot toy as claimed in claim 1, wherein a standing posture form and a forward bent posture form are taken by the robot toy according to movement of the control unit.
 - 3. (Canceled)

4. (Previously Presented) The robot toy as claimed in claim 1, wherein the frame is arranged in a trunk portion of the toy, the first toy component is a lower jaw, and the second toy component is an upper jaw.

Claims 5-6 (Canceled)

- 7. (Previously Presented) The robot toy as claimed in claim 9, wherein the frame is arranged in a trunk portion of the toy, the first toy component is a lower jaw, and the second toy component is an upper jaw.
 - 8. (Canceled)
- 9. (Currently Amended) A drive device for a toy that changes its form, comprising: a four section link including a link, a frame that faces the link, and two swinging links that face each other;
 - a first toy component arranged ondirectly connected to the link; and
- a second toy component arranged on one of the two swinging links that face each other; wherein:

the one of the two swinging links extends to an opposite side with respect to the frame and a tip thereof rotatably and swingably <u>directly</u> engages with a rotating disk at an eccentric position; and

the first and second toy components are rotated and perform opening and closing movements relative to each other by rotating the rotating disk, before or after the form change.

- 10. (Currently Amended) A robot toy, comprising:
- a control unit formed by a movable leg of the robot toy,
- a clutch to transmit motor power:
- a switch:
- a four section link including a link, a frame that faces the link, and first and secondswinging links that face each other;
 - a box to house the motor and the clutch:
 - a first shaft that couples the first swinging link with the frame;
 - a second shaft that couples the second swinging link with the frame, the second shaft

being parallel with the first shaft;

a third shaft that connects the box with the frame, the third shaft being perpendicular to the first and second swinging linksshafts;

a first toy component arranged ondirectly connected to the link; and

a second toy component arranged on the first swinging link; wherein

the clutch is engaged by moving the control unit to change the form of the toy robot, and the motor power is transmitted so that a part of the robot toy conducts at least one among up and down movement, rotating movement, or opening and closing movement,

the switch is switched by moving the control unit, and at least one among number of revolutions of the motor, luminescent color in the robot toy, or sound production, is changed before and after the form change,

the first swinging link extends to an opposite side with respect to the frame and a tip thereof rotatably and swingably <u>directly</u> engages with a rotating disk at an eccentric position, and

the frame swings from side to side around the third shaft as a center, the first swinging link swings up and down around the first shaft as a center and the second swinging link swings up and down around the second shaft as a center, allowing the first and second toy components to be rotated to perform opening and closing movements relative to each other by rotating the rotating disk, before or after the form change.

- 11. (Currently Amended) A drive device for a toy that changes its form, comprising:
- a four section link including a link, a frame that faces the link, and first and second swinging links that face each other;
 - a box to house a motor and a clutch;
 - a first shaft that couples the first swinging link with the frame;
- a second shaft that couples the second swinging link with the frame, the second shaft being parallel with the first shaft;
- a third shaft that connects the box with the frame, the third shaft being perpendicular to the first and second swinging linksshafts;
 - a first toy component arranged ondirectly connected to the link; and
 - a second toy component arranged on the first swinging link; wherein

the first swinging link extends to an opposite side with respect to the frame and a tip thereof rotatable and swingably directly engages with a rotating disk at an eccentric position; and

the frame swings from side to side around the third shaft as a center, the first swinging link swings up and down around the first shaft as a center and the second swinging link swings

up and down around the second shaft as a center, allowing the first and second toy components to be rotated to perform opening and closing movement relative to each other by rotating the rotating disk, before or after the form change.